



Differential graded manifolds, infinity-stacks and generalized geometries

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(notes taken by Christoph Wockel)

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I dg manifolds - general theory

dg-manifolds are supermanifolds with certain additional structures. First some generalities on supermanifolds and super vectorspaces:

I.1 Linear Algebra

V monoidal category, e.g. Set , Vect , \mathcal{C} a V -enriched category. For objects a, b of \mathcal{C} (write $c, d \in \mathcal{C}$), write $\mathcal{C}(a, b)$ for the hom-object in V .

$$c \in \mathcal{C} \Rightarrow \mathcal{C}[c] = \mathcal{C}(\cdot, c) \in V^{\text{cop}}$$

Yoneda Lemma: $V = \text{Set}$, $c \in \mathcal{C}$, $F \in \text{Set}^{\mathcal{C}^{\text{op}}} \Rightarrow F(c) \cong \text{Set}^{\mathcal{C}^{\text{op}}}(\underline{\subseteq}, F)$. Also works in the enriched setting, at least for concrete categories, such as Vect .

Definition I.1. Let Γ be an abelian group, viewed as a discrete category enriched in Vect . A Γ -graded vector space is defined to be a functor $\Gamma \rightarrow \text{Vect}$. Then Vect^{Γ} denotes the category of Γ -graded vector spaces. ■

- Each $V \in \text{Vect}^{\Gamma}$ is given by a collection $V = (V_{\gamma})_{\gamma \in \Gamma}$ and $\text{Vect}^{\Gamma}(V, W) = \prod_{\gamma \in \Gamma} \text{Vect}(V_{\gamma}, W_{\gamma})$.
- For $\gamma \in \Gamma$ we thus have $\underline{\gamma} = \Gamma[\gamma] = \text{Vect}^{\Gamma}(\cdot, \gamma) = \mathbb{k}$ concentrated in degree γ .
- By Yoneda, $V_{\gamma} = \text{Vect}^{\Gamma}(\underline{\gamma}, V)$. Representable functors are otherwise known as *lines*.
- (note: $\Gamma(\gamma, \gamma') = \mathbb{k}$ iff $\gamma = \gamma'$ and 0 otherwise)

Tensor product:

$$(V \otimes W)_{\gamma} = \bigoplus_{\gamma' + \gamma'' = \gamma} V_{\gamma'} \otimes W_{\gamma''}$$

Braiding

$$\epsilon : \Gamma \rightarrow \mathbb{Z}_2 \text{ parity map, } \tau_{V, W} : V \otimes W \rightarrow W \otimes V, \quad v \otimes w \mapsto (-1)^{\epsilon(\deg(v))\epsilon(\deg(w))} w \otimes v$$

If $\phi : \Gamma' \rightarrow \Gamma$ is a group homomorphism, then we obtain functors

$$\begin{array}{ccc} & \xrightarrow{\phi!} & \\ \text{Vect}^{\Gamma'} & & \text{Vect}^{\Gamma} \\ & \xleftarrow{\phi^*} & \end{array}$$

$(\varphi!V)_{\gamma'} = \bigoplus_{\gamma \in \varphi^{-1}(\gamma')} V_{\gamma}$. In particular, we obtain

$$\text{Vect}^{\Gamma} \xrightarrow{\epsilon!} \text{Vect}^{\mathbb{Z}_2}$$

- $\text{Vect}^{\Gamma}(V \otimes W, U) \cong \text{Vect}^{\Gamma}(V, \underline{\text{Vect}}^{\Gamma}(W, U))$ with $\underline{\text{Vect}}^{\Gamma}(W, U)_{\gamma} \cong \prod_{g'} \text{Vect}(W_{\gamma'}, U_{\gamma'+\gamma})$
- dual: $V^* = \underline{\text{Vect}}^{\Gamma}(V, \mathbb{0})$
- shift: $V[\gamma] = \underline{\text{Vect}}^{\Gamma}(\gamma, V)$

Definition I.2. V is *finite-dimensional* if V^{tot} is so. $\dim(V) = \sum_{\gamma} (\dim(V_{\gamma})) e_{\gamma} \in \mathbb{N}[\Gamma]$, and $\text{sdim}(V) = \sum_{\gamma} (-1)^{\epsilon(\gamma)} \dim V_{\gamma} \in \mathbb{Z}$ ■

- typically, $\Gamma = \mathbb{Z}, \mathbb{Z}_2, \mathbb{Z} \times \mathbb{Z}_2$
- a complex will always be a cochain complex, the differential always increases degrees by 1 (and is odd)
- \mathbb{N} -graded v.s. are considered as \mathbb{Z} -graded concentrated in $\text{deg} \geq 0$. If V is \mathbb{N} -graded, then V^* is $-\mathbb{N}$ -graded
- \mathbb{N} -grading \Leftrightarrow action of a multiplicative monoid $\mathbb{M}(\mathbb{k})$
- \mathbb{Z} -grading \Leftrightarrow action of a multiplicative group $\mathbb{G}(\mathbb{k})$ if \mathbb{k} is algebraically closed of characteristic 0.
- \mathbb{Z}_2 -grading \Leftrightarrow action of $\mu_2 = \{\pm 1\}$.

I.2 Superdomains

Definition I.3. For $U \subseteq \mathbb{R}^n$ open, $U^{n|m} = (U, \mathcal{O}_{U^{n|m}})$, where $\mathcal{O}_{U^{n|m}}(U') = C^{\infty}(U') \otimes \Lambda[\xi^1, \dots, \xi^m]$ as a \mathbb{Z}_2 -graded commutative algebra. A morphism

$$U^{n|m} \rightarrow V^{n|m}$$

is just a map pf locally ringed spaces (parity-preserving), i.e. $f_0 : U \rightarrow V$ is continuous and $f^* : \mathcal{O}_V \rightarrow (f_0)_* \mathcal{O}_U$ ■

It can be shown that

- f_0 is C^{∞}
- f is determined by its values on coordinates

$$U^{n|m} \rightarrow V^{p|q} \dots$$

Definition I.4. A supermanifold is a locally ringed space $M = (M_0, \mathcal{O}_M)$, locally isomorphic to a superdomain. Denote the corresponding category by SM ■

Points: For \mathcal{C} any category, denote by $Y : \mathcal{C} \rightarrow \text{Set}, c \mapsto \mathcal{C}[c] = \mathcal{C}(\cdot, c) = \underline{c}$. $\mathcal{C}(a, b) \cong \text{Set}^{\text{cop}}(\underline{a}, \underline{b}) \rightsquigarrow \mathcal{C}[c]$ is the functor of points on c . $b \xrightarrow{p} c$ is a "b-point" in \mathcal{C}

$$\begin{array}{ccc} c' & \xleftarrow{f} & c \\ & \swarrow fp & \uparrow p \\ & & b \end{array}$$

("fp is the value on f at the point p")

- This language of points can be extended to not necessarily representable presheaves
- if $*$ $\in \mathcal{C}$ is terminal, then \mathcal{C} is *concrete* if u is faithful

$$\begin{array}{ccc} \mathcal{C} & \xrightarrow{u} & \text{Set} \\ & \searrow y & \nearrow \iota^* \\ & \text{Set}^{\mathcal{C}^{\text{op}}} & \end{array}$$

for $\iota : \{*\} \hookrightarrow \mathcal{C}$

- SM is *not* concrete, but if $\mathcal{P} = \text{Odd}_0 = \{(*, \Lambda[\xi^1, \dots, \xi^m])\} \hookrightarrow \text{SM}$, then

$$\begin{array}{ccc} \mathcal{C} & \xrightarrow{u} & \text{Set}^{\mathcal{P}^{\text{op}}} \\ & \searrow & \nearrow \\ & \text{Set}^{???^{\text{op}}} & \end{array}$$

is faithful

Uses of the functor of points:

- $\text{SM}^{\text{op}} \rightarrow \text{Vect}$, $M \mapsto C^\infty(M)_0$ (resp. $M \mapsto C^\infty(M)_1$) are represented by \mathbb{R} (resp. $\mathbb{R}^{0|1}$)

Corollary I.5. $\text{Vect}_f^{\mathbb{Z}_2} \cong \text{Vect}(\text{SM})$ (*vector space objects in SM*)

II Courant algebroids and Courant-Dorfman algebras

$\mathcal{C} \rightarrow \text{Set}^{\mathcal{C}^{\text{op}}}$ $X \mapsto C[X] = \mathcal{C}(\cdot, X)$ (Joneda embedding)

$$\begin{array}{ccc} X & \xleftarrow{p} & B \\ & \searrow p\varphi & \uparrow \varphi \\ & & B' \end{array} \qquad \begin{array}{ccc} X & \xleftarrow{f} & B \\ & \searrow fb := f(b) & \uparrow b \\ & & B \end{array}$$

(this always holds). At the other extreme, we have
For $*$ $\in \mathcal{C}$, consider

$u(x) = \mathcal{C}(*, x)$. Then \mathcal{C} is concrete $\Leftrightarrow u$ is faithful
The intermediate step is: $* \subseteq \mathcal{P} \hookrightarrow \mathcal{C}$

E.g.: $\mathcal{C} = \text{SM}$, $\mathcal{P} = \text{Odd}_0 = \text{Grass}_f^{\text{op}}$ (connected odd super manifolds). For $f : U^{P|q} \rightarrow \mathbb{R}$, consider $y = f_0(x) + \frac{1}{2}\xi\xi f_2(x)$,

$$\begin{array}{ccc} \mathbb{R} & \xleftarrow{\quad} & U^{n|m} \\ & \searrow & \uparrow \\ & & \mathbb{R}^{0|k} \end{array}$$

detects everything.

II.1 Even and odd tangent bundles

Let $M \in \text{SM}$, $M \xleftarrow{p} B$ a point.

Definition II.1. An even (odd) derivation at p is a linear even (odd) map $D : C^\infty(M) \rightarrow C^\infty(B)$ satisfying

$$D(fg) = (Df)g(p) + (-1)^{\deg(D)\deg(f)} f(p)Dg.$$

With this we set $\text{Der}_{0(1)}(M, p) = \{\text{all even (odd) derivations at } p\}$ and

$$\text{Der}_{0(1)}(M)(B) = \coprod_{b:B \rightarrow M} \text{Der}_{0(1)}(M, b).$$

This defines a presheaf $\text{Der}_{0(1)}(M) : \text{SM}^{\text{op}} \rightarrow \text{Set}$. ■

Definition II.2. An even tangent vector at p is a map $B \times \mathbb{R} \xrightarrow{\gamma} M / \sim$

- $\gamma|_{B \times \{0\}} = p$
- $\gamma \sim \gamma'$ first order equivalence

$\Rightarrow \text{Tan}_0(M) : \text{SM}^{\text{op}} \rightarrow \text{Set}$. An odd tangent vector at p is a map $B \times \mathbb{R}^{0|1} \xrightarrow{\gamma} M$ s.th. $\gamma|_{B \times \{0\}} = 0$ (this is just a family of odd curves parametrized by B). $\Rightarrow \text{Tan}_1 : \text{SM}^{\text{op}} \rightarrow \text{Set}$ ■

Proposition II.3. $\text{Der}_{0(1)}(M)$, $\text{Tan}_{0(1)}(M)$ are isomorphic and representable by supermanifolds TM (resp. ΠTM). Moreover, these have a natural vector bundle structure s.th. the space of sections is the same as the space of even (resp. odd) vector fields on M .

Corollary II.4. The presheaf $\underline{\text{SM}}(\mathbb{R}^{0|1}, M) : B \mapsto \text{SM}(B \times \mathbb{R}, M)$ is representable by $\Pi TM \cong M^{\mathbb{R}^{0|1}}$

Proposition II.5. $\underline{\text{SM}}(X, Y)$ is representable for all $Y \Leftrightarrow X \in \text{Odd}_c$ (where the subscript c denotes finite unions of superpoints).

II.2 Composition of internal homs

Want to define $\underline{C}(X, Z) \times \underline{C}(Z, Y) \rightarrow \underline{C}(X, Y)$. For $b \in \mathcal{C}$, define

$$C(Y \times b, Z) \times C(X \times b, Y) \rightarrow C(X \times b, Z), \quad (f, g) \mapsto f(g \times 1)(1 \times \Delta)$$

In particular, $\underline{C}(Y, Y)$ is a presheaf of monoids acting for all $X \in \mathcal{C}$ from the left on $\underline{C}(X, Y)$ and for all $Z \in \mathcal{C}$ from the right on $\underline{C}(Y, Z)$.

Corollary II.6. $\Pi TM \cong M^{\mathbb{R}^{0|1}}$ has a natural smooth action of the monoid objects $\mathbb{R}^{0|1 \mathbb{R}^{0|1}} \cong \mathbb{M}_m(\mathbb{R}) \rtimes \mathbb{R}^{0|1}$

Note that a right action of $\mathbb{M}_m(\mathbb{R}) \rtimes \mathbb{R}^{0|1}$ is the same as an \mathbb{N} -grading and an odd differential of degree +1.

$\Omega(M) \cong C^\infty(\Pi TM)$. Then the action is just the usual grading of differential forms, together with the de Rham differential.

Definition II.7. A differential \mathbb{N} -graded supermanifold is an $M \in \text{SM}$ with a right action of $\mathbb{R}^{0|1 \mathbb{R}^{0|1}}$. A dg-manifold is the same such that (-1) acts as the parity involution. ■

Fact: a dg-manifold is the same thing as a locally ringed space (M, \mathcal{O}_M) (in \mathbb{N} -graded commutative algebras over \mathbb{R}), which is locally isomorphic to (U, \mathcal{O}_U) (+ a derivation of degree +1 and square 0), where

$$\mathcal{O}_U(U') = C^\infty(U') \otimes S(V^*)$$

where $U \subseteq \mathbb{R}^n$ is open and V is an $(-\mathbb{N})$ -graded vector space.

III Presheaves etc.

Recall: A dg-manifold (M_0, \mathcal{O}, d) is locally isomorphic to $(U \subseteq \mathbb{R}^n, \mathcal{O}_U = C_U^\infty \otimes S^\bullet V^*)$. This is equivalently given by a supermanifold (M, \mathcal{O}_M) , together with a right action of $\mathbb{R}^{0|1|0|1} = \mathbb{M}_n(\mathbb{R}) \rtimes \mathbb{R}^{0|1}$ (such that -1 acts as parity involution)

III.1 Some adjunctions:

- $\text{dgMan} \xleftarrow{u_{0!}} \text{Man}$, $u_{0!}(N) = N$ with zero grading and d
- $\text{dgMan} \xrightarrow{u_0} \text{Man}$, $u_0(N) = \Pi TN$ with the canonical grading and d the de Rham differential.
- $\text{dgMan} \xleftarrow{u_{0*}} \text{Man}$

The unit $M \mapsto u_{0*}u_0M = \Pi TM_0$ is called the *anchor map*.

- $\text{dgMan} \xleftarrow{u_!} \text{GrMan}$, $u_!(N) = N$ with zero d
- $\text{dgMan} \xrightarrow{u} \text{GrMan}$
- $\text{dgMan} \xleftarrow{u_*} \text{GrMan}$, $u_*(N) = T[1]N$ ($\deg(dx) = \deg(x) + 1$)

Using u_{0*} , one can define maps from a manifold N to a dg-manifold M to be a dg-map from $T[1]N$ to M . One can also define homotopies of such maps to be a dg-map $T[1](N \times I) \rightarrow M$ with specified boundary conditions. In fact, the category dgMan is naturally enriched in $\text{Set}^{\Delta^{\text{op}}}$ w.r.t.

$$\text{Map}(M, M')_n := \text{dgMan}(M \times T[1]\Delta^n, M').$$

III.2 The tangent complex

$M = (M_0, \mathcal{O}_M, d)$, a linearized action of $\mathbb{R}^{0|1\mathbb{R}^{0|1}}$ on the restricted bundle $T|_{M_0} M$ gives rise to a cochain complex

$$\mathbb{T}M = (T_{-n} \xrightarrow{\delta_n} \dots \xrightarrow{\delta_3} T_{-2} \xrightarrow{\delta_2} T_{-1} \xrightarrow{\delta_1 := p} T_0 = TM_0)$$

the integer n is called the *degree* of M (the highest degree of a local coordinate). Here δ in the dual on the linear part of d .

$\dim H^i(\mathbb{T}_x M, \delta)$ can vary with x , but $\text{sd}(M) = \sum (-1)^i \dim H^i = \sum (-1)^i \dim T_i \in \mathbb{Z}$ does not.

Example III.1. • H : a vector space $n > 0$, $H[n] = (\text{pt}, S(H[n])^*) = (\text{pt}, \rho^* h^*[-n])$. These are important for they play the role of Eilenberg–Mac Lane spaces for dg-manifolds, i.e.

$$\begin{aligned} \text{dgMan}(T[1]N, H[n]) &\cong \Omega^{n, \text{cl}}(N, h) \\ \text{dgMan}(T[1]N, H[n])/\text{homotopy} &\cong H_{\text{dR}}^n(N, h) \end{aligned}$$

- $\deg(M) = 1$,

$$M = A[1] = (M_0, S^\bullet(A[1])^*) = (M_0, S(A^*[-1])) = (M_0, \Lambda A^*)$$

for $A \rightarrow M$ a vector bundle. A differential is the same thing as a Lie algebroid structure on A . ■

$\text{Vect}(M)$ (differential operators on smooth functions) is a differential graded Lie algebra concentrated in degrees $[-n, \infty)$, $D = \{\cdot, d\}$

($n = 1$): $\text{Vect}^{-1}(A[1]) \cong \Gamma(A) \ni v \mapsto \iota_v, \{\iota_v, \iota_v\} = 0$. Then the derived bracket $\{\iota_v \{ \iota_w, d \}\} = \iota_{[v, w]}$ (Cartan) defines a bracket on $\Gamma(A)$. $L^0 = Z^0(\text{Vect}(M))$ infinitesimal automorphisms of (M, d) , $L^{-i} = \text{Vect}^{-i}(M)$ for $i > 0$, $L^{-n} \rightarrow \dots \rightarrow L^{-1} \rightarrow L^0$ is also dgla

($n = 1$): $L^{-1} \xrightarrow{D} L^0$ is a Lie algebra crossed module.

($n > 1$): $\{\cdot, \cdot\}$ on $L^{-n} \rightarrow \dots \rightarrow L^{-1} \rightarrow L^0$ does not vanish, $[\cdot, \cdot] = \{\cdot, d, \cdot\}$ is not skew-symmetric any more, so we obtain only a Leibnitz algebra. **Higher derived brackets:** $[v, w, u] := \pm\{v, \{w, \{u, d\}\}\}$ (and so on) (**Ex.:** A principal $\mathbb{R}[n]$ -bundle over $T[1]M_0$ (infinitesimal $(n-1)$ -gerbe), classified by $H^{n+1}(M)$).

($n = 2$): $\text{Vect}^{<0}(P) : \text{Vect}^{-2}(P) \cong C^\infty(M_0)$ ($f \frac{\partial}{\partial t}$ for t a coordinate on $\mathbb{R}[2]$)

$$0 \rightarrow \Omega^1(M) \rightarrow \text{Vect}^{-1}(P) := E \rightarrow \text{Vect}(M) \rightarrow 0,$$

$\{\cdot, \cdot\} : E \otimes E \rightarrow C^\infty(M)$ and $[\cdot, \cdot] : E \otimes_{\mathbb{R}} E \rightarrow E$ a Leibnitz algebra + compatibility conditions. This defines a Courant algebroid and gives rise to "generalised differential geometry" in the sense of Hitchin and Gualtieri.